

Port Maps for Irreversible Interface Relations

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Introduction

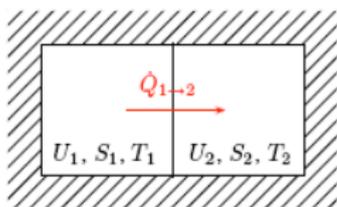
Introduction

Motivation : Port maps for Irreversible Port Hamiltonian Systems

- Irreversible Hamiltonian Systems :
 - geometry represents the topology, the energy fluxes within and with its environment
 - represents the reversible and irreversible phenomena
- Port conjugated output not defined for Irreversible Port Hamiltonian Systems requires to distinguish
 - interface which are subject to irreversible phenomena such as Fourier's law or not
 - for such interface make appear the entropy creation at the interface and deduce the port maps

Heat exchanger : failure of Hamiltonian framework

The model



Thermodynamic model given by Gibbs' relation : $dU_i = T_i dS_i$ where

$$T_i = \frac{\partial U_i}{\partial S_i}(S_i), \quad i = 1, 2$$

Heat flux due to conducting wall : $\dot{Q}_{1 \rightarrow 2} = \lambda (T_1 - T_2)$ with λ the heat conduction coefficient

Continuity of heat flux : $\dot{Q}_{1 \rightarrow 2} = -T_1 \frac{dS_1}{dt} = T_2 \frac{dS_2}{dt}$

lead to the **entropy balance equations**

$$\frac{d}{dt} \begin{pmatrix} S_1 \\ S_2 \end{pmatrix} = \begin{pmatrix} -\frac{\dot{Q}_{1 \rightarrow 2}}{T_1} \\ \frac{\dot{Q}_{1 \rightarrow 2}}{T_2} \end{pmatrix} = \lambda \left(\frac{1}{T_2} - \frac{1}{T_1} \right) \begin{pmatrix} -T_2 \\ T_1 \end{pmatrix}$$

Heat exchanger : failure of Hamiltonian framework

Heat conduction process : pseudo-Hamiltonian formulation

The Hamiltonian-like formulation :

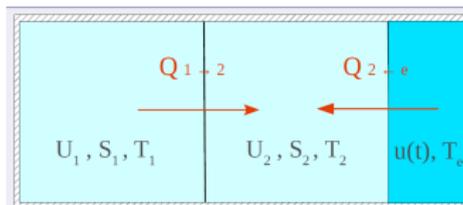
$$\frac{d}{dt} \begin{pmatrix} S_1 \\ S_2 \end{pmatrix} = \lambda \underbrace{\begin{pmatrix} 1 & -1 \\ T_2 & T_1 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}}_{J(T)} \begin{pmatrix} T_1 \\ T_2 \end{pmatrix}$$

with $T_i = \frac{\partial(U_1+U_2)}{\partial S_i}(S) = \frac{\partial U_i}{\partial S_i}(S_i)$.

- 1 $J(T)$ is skew-symmetric but depend on the temperature and not the entropy.
- 2 the map from the gradient of the total energy $\frac{\partial(U_1+U_2)}{\partial S}$ to the generalized velocities **is not linear** !

Heat exchanger with thermostat

Two systems 1 and 2 interact through a heat conducting wall and system 2 interacts with a thermostat at temperature T_e :
 input map affine in the control ! Port conjugated output ?



The entropy balance equations

$$\begin{bmatrix} \dot{S}_1 \\ \dot{S}_2 \end{bmatrix} = \lambda \begin{bmatrix} \frac{T_2(S_2)}{T_1(S_1)} - 1 \\ \frac{T_1(S_1)}{T_2(S_2)} - 1 \end{bmatrix} + \lambda_e \begin{bmatrix} 0 \\ \frac{T_e(t)}{T_2(S_2)} - 1 \end{bmatrix}$$

where S_1 and S_2 are the entropies of subsystem 1 and 2, $T_e(t)$ a time dependent external heat source and $\lambda > 0$ and $\lambda_e > 0$ denotes Fourier's heat conduction coefficients of the internal wall and the external wall.

Complete the Irreversible Port Hamiltonian Systems

Irreversible Port Hamiltonian Systems (IPHS) is the nonlinear control system

$$\frac{dx}{dt} = m \left(x, \frac{\partial U}{\partial x}, \frac{\partial S}{\partial x} \right) J \frac{\partial H}{\partial x}(x) + W \left(x, \frac{\partial H}{\partial x} \right) + g \left(x, \frac{\partial H}{\partial x} \right) u, \quad (1)$$

generated by two function $H(x)$ and $S(x)$!

H. Ramirez Estay , B. Maschke and D. Sbarbaro, Irreversible port-Hamiltonian systems: A general formulation of irreversible processes with application to the CSTR, Chemical Engineering Science, Volume 89, pp. 223-234 15 February 2013

H. Ramirez Estay , B. Maschke and D. Sbarbaro, Irreversible port Hamiltonian systems, European Journal of Control, Special issue "Lagrangian and Hamiltonian methods for non-linear control", A. Macchelli and C. Secchi eds., Volume 19, n° 6, pp.513-520, 2013

H. Ramirez, Y. Le Gorrec, B. Maschke, F. Couenne, Passivity Based Control of Irreversible Port Hamiltonian Systems, Automatica, Vol.64, pp. 105-111, Feb. 2016

Port Hamiltonian systems: conjugated port maps

Port Hamiltonian systems: conjugated port maps

Port Hamiltonian systems

Port Hamiltonian Systems are non-linear control systems

$$\begin{pmatrix} \frac{dx}{dt} \\ -y \end{pmatrix} = \begin{pmatrix} J(x) & g(x) \\ -g(x)^\top & 0 \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial x} \\ u \end{pmatrix} \quad (2)$$

defined by

- 1 the state vector $x \in \mathbb{R}^n = \mathcal{X}$,
- 2 the Hamiltonian function $H(x) : \mathcal{C}^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}$
- 3 the skew-symmetric structure matrix $J(x) \in \mathbb{R}^n \times \mathbb{R}^n$
- 4 the input matrix $g(x)$

The anti-adjoint maps defined by $g(x)$ and $-g^\top(x)$ define pairs of conjugated port variables (u, y) and the balance equation

$$\frac{dH}{dt} = y^\top u$$

Port Hamiltonian systems

The map $T^* \mathcal{X} \times U \rightarrow T \mathcal{X} \times Y$ defined by

$$\begin{pmatrix} J(x) & g(x) \\ -g(x)^\top & 0 \end{pmatrix} \quad (3)$$

extends the (pseudo-)Poisson bracket associated with the skew-symmetric matrix $J(x)$ and may be seen as arising from the (pseudo-)Hamiltonian system

$$\begin{pmatrix} \frac{dx}{dt} \\ \frac{d\xi}{dt} \end{pmatrix} = \begin{pmatrix} J(x) & g(x) \\ -g(x)^\top & 0 \end{pmatrix} \begin{pmatrix} \frac{\partial H}{\partial x}(x) \\ \frac{\partial \bar{H}_u}{\partial \xi}(\xi) \end{pmatrix}$$

with $\xi(t) \in \mathbb{R}^m$ is the state variable of the environment and Hamiltonian function being linear in the input u :

$$\bar{H}_u(\xi) = u^\top \xi \quad (4)$$

and projected parallel to the environment's state.

Irreversible Port Hamiltonian systems

Irreversible Port Hamiltonian systems

A class of quasi-Hamiltonian systems : irreversible Hamiltonian systems

Irreversible HS are defined by the following dynamic equation

$$\dot{x} = \gamma\left(x, \frac{\partial U}{\partial x}\right) \underbrace{\frac{\partial S}{\partial x}(x)^T J \frac{\partial U}{\partial x}(x) J \frac{\partial U}{\partial x}(x)}_{=\{S, U\}_J}$$

with

- 1 the state vector $x \in \mathbb{R}^n$, the energy function $U(x) : \mathcal{C}^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}$ and the entropy function $S(x) : \mathcal{C}^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}$.
- 2 the constant skew-symmetric structure matrix $J \in \mathbb{R}^n \times \mathbb{R}^n$
- 3 a positive definite function: $\gamma(x, \frac{\partial U}{\partial x}) = \hat{\gamma}(x) : \mathcal{C}^\infty(\mathbb{R}^n) \rightarrow \mathbb{R}_+^*$.

Irreversible Hamiltonian systems : energy and entropy balance equations

The conservation equation of the internal energy,

$$\frac{dU}{dt} = 0, \quad (5)$$

follows from the skew-symmetry of the structure matrix J .

The irreversible entropy production

$$\frac{dS}{dt} = \gamma\left(x, \frac{\partial U}{\partial x}\right) \{S, U\}_J \geq 0$$

Irreversible Port Hamiltonian arise naturally for heat exchangers, Chemical reactors, etc..:

- the bracket $\{S, H\}_J$ is the **thermodynamic force**
- the function $\gamma\left(x, \frac{\partial U}{\partial x}\right)$ the **irreversible phenomenon relation**

Canonical example : the heat exchanger

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Heat conduction : irreversible Hamiltonian system

$$\begin{aligned} \frac{d}{dt} \begin{pmatrix} S_1 \\ S_2 \end{pmatrix} &= \lambda \left(\frac{1}{T_1} - \frac{1}{T_2} \right) \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} \\ &= \underbrace{\frac{\lambda}{T_1 T_2}}_{=\gamma} \underbrace{(T_1 - T_2)}_{=\{S, U\}_J} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \underbrace{\begin{bmatrix} T_1 \\ T_2 \end{bmatrix}}_{dU(S)} \end{aligned}$$

with :

- **internal energy** U , co-energy variables : $\frac{\partial U}{\partial S_i} = T_i(S_i)$
- **entropy function** : $\mathcal{S} = S_1 + S_2$ and
 $\frac{\partial \mathcal{S}}{\partial x}^\top J \frac{\partial U}{\partial x} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}^\top \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = T_1 - T_2$: **driving force**
- **positive function** : $\gamma \left(\frac{\partial U}{\partial S} \right) = \frac{\lambda}{T_1 T_2} > 0$ as $T_1 > 0$ and $T_2 > 0$:
Fourier's law

Heat exchanger : internal energy and entropy balance equations

Energy and entropy balance equations

- ① **Conservation of the total internal energy** due to the skew-symmetry of $J(T)$:

$$\frac{d}{dt}(U_1 + U_2) = (T_1, T_2) \lambda \begin{pmatrix} \frac{1}{T_2} & -\frac{1}{T_1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} T_1 \\ T_2 \end{pmatrix} = 0$$

- ② **Increase of the total entropy** due to the non-linear map :

$$\frac{d}{dt}(S_1 + S_2) = (1, 1) \lambda \begin{pmatrix} \frac{1}{T_2} & -\frac{1}{T_1} \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} T_1 \\ T_2 \end{pmatrix} = \lambda \frac{(T_1 - T_2)^2}{T_1 T_2} \geq 0$$

Reversible-Irreversible Hamiltonian systems

$$\frac{dx}{dt} = \left[\underbrace{J_0(x)}_{\text{reversible}} + \underbrace{\gamma\left(x, \frac{\partial H}{\partial x}\right) \{S, H\}_J J}_{\text{irreversible coupling}} \right] \frac{\partial U}{\partial x}(x) \quad (6)$$

where

(i) $J_0(x)$ and J the structure matrix of a Poisson bracket

(ii) $\gamma\left(x, \frac{\partial H}{\partial x}\right) > 0$

(iii) the entropy function $S(x)$ a Casimir function of the Poisson structure matrix $J_0(x)$

Satisfies the two balance equations:

- conservation equation of the internal energy, $\frac{dU}{dt} = 0$,
- entropy balance equation with irreversible entropy production

$$\frac{dS}{dt} = \gamma\left(x, \frac{\partial U}{\partial x}\right) \{S, U\}_J^2 \geq 0$$

Irreversible Port Hamiltonian systems

Irreversible Port Hamiltonian systems

Port map arising from a IHS: extended system

Consider

- state variable $x(t) \in \mathbb{R}^n$
- environment state $\xi(t) \in \mathbb{R}^m$
- *constant* structure matrix defined by $g \in \mathbb{R}^{n \times m}$

$$J_{\text{port}} = \begin{pmatrix} 0 & g \\ -g^\top & 0 \end{pmatrix}$$

- energy function

$$H_{\text{tot}}(x, \xi) = H(x) + u^\top \xi, \quad u \in \mathbb{R}^m$$

- entropy function

$$S_{\text{tot}}(x, \xi) = S(x) + \tau^\top \xi, \quad \tau \in \mathbb{R}^m$$

Port map arising from a IHS: Irreversible Port Hamiltonian System

$$\begin{aligned} \begin{pmatrix} \frac{dx}{dt} \\ -y \end{pmatrix} &= \gamma_{\text{port}} \left(x, \frac{\partial H}{\partial x}, u \right) \{S_{\text{tot}}, H_{\text{tot}}\}_{J_{\text{port}}} \underbrace{J_{\text{port}} \begin{pmatrix} \frac{\partial H}{\partial x} \\ u \end{pmatrix}}_{= \begin{pmatrix} g u \\ -g^{\top} \frac{\partial H}{\partial x} \end{pmatrix}} \end{aligned}$$

where $\{S_{\text{tot}}, H_{\text{tot}}\}_{J_{\text{port}}} = \left[\left(g^{\top} \frac{\partial S}{\partial x} \right)^{\top} u - \tau^{\top} \left(g^{\top} \frac{\partial H}{\partial x} \right) \right]$

- $u = \frac{\partial H_{\text{tot}}(x, \xi)}{\partial \xi}$ and $\tau = \frac{\partial S_{\text{tot}}(x, \xi)}{\partial \xi}$
- $\gamma_{\text{port}} \left(x, \frac{\partial H}{\partial x}, u \right)$ is a strictly positive function.

Irreversible Port Hamiltonian systems

An Irreversible Port Hamiltonian system (IPHS)

$$\frac{dx}{dt} = \gamma\left(x, \frac{\partial H}{\partial x}\right) \{S, H\}_J J \frac{\partial H}{\partial x}(x) \quad (7)$$

$$+ \gamma_{\text{port}}\left(x, \frac{\partial H}{\partial x}, u\right) \left[\left(g^\top \frac{\partial S}{\partial x}\right)^\top u - \tau^\top \left(g^\top \frac{\partial H}{\partial x}\right) \right] g u \quad (8)$$

$$y = \gamma_{\text{port}}\left(x, \frac{\partial H}{\partial x}, u\right) \left[\left(g^\top \frac{\partial S}{\partial x}\right)^\top u - \tau^\top \left(g^\top \frac{\partial H}{\partial x}\right) \right] g^\top \frac{\partial H}{\partial x} \quad (9)$$

(i) a real function $\gamma_{\text{port}}\left(x, \frac{\partial H}{\partial x}, u\right)$, strictly positive function

(iv) the input vector field $g \in \mathbb{R}^{n \times m}$ and the vector $\tau \in \mathbb{R}^m$ associated with the ports of the system.

Energy and entropy balance equations

The energy balance equation

$$\frac{dH}{dt} - y^\top u = 0$$

where $y^\top u$ is the power flowing into the system

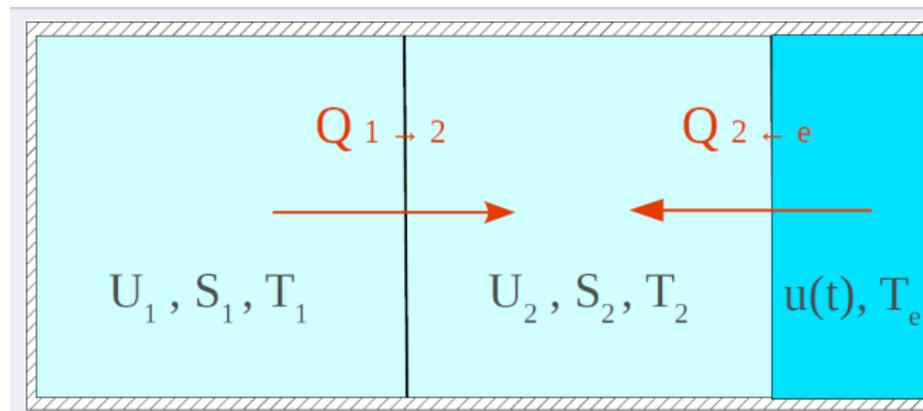
The entropy balance equation

$$\begin{aligned} \frac{dS}{dt} - \tau^\top y &= \gamma\left(x, \frac{\partial U}{\partial x}\right) \{S, U\}_J^2 \\ &+ \gamma_{\text{port}}\left(x, \frac{\partial H}{\partial x}, u\right) \left[\left(g^\top \frac{\partial S}{\partial x} \right)^\top u - \tau^\top \left(g^\top \frac{\partial H}{\partial x} \right) \right]^2 \geq 0 \end{aligned}$$

where the term $\tau^\top y$ corresponds to the entropy flowing out the environment (to the system).

2 cells with thermostat

Two simple thermodynamic systems 1 and 2 interact through a heat conducting wall and system 2 interacts with a thermostat at temperature T_e .



The entropy balance equations

$$\begin{bmatrix} \dot{S}_1 \\ \dot{S}_2 \end{bmatrix} = \lambda \begin{bmatrix} \frac{T_2(S_2)}{T_1(S_1)} - 1 \\ 1 \end{bmatrix} + \lambda_e \begin{bmatrix} 0 \\ \frac{T_e(t)}{T_1(S_1)} - 1 \end{bmatrix}$$

Heat conduction : irreversible Hamiltonian system

$$\frac{d}{dt} \begin{bmatrix} S_1 \\ S_2 \end{bmatrix} = \underbrace{\frac{\lambda}{T_1 T_2}}_{=\gamma} \underbrace{(T_1 - T_2)}_{=\{S, U\}_J} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \underbrace{\begin{bmatrix} T_1 \\ T_2 \end{bmatrix}}_{dU(S)} + \underbrace{\frac{\lambda_e}{T_2 u}}_{=\gamma_{\text{port}}(T_2, u)} (u - T_2) \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{=g} u$$

and output being the entropy flux leaving the environment (with respect to the temperature $u = T_e$ of the environment).

$$y = \frac{\lambda_e}{u T_2} [(u - T_2)] \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \frac{\lambda_e (u - T_2)}{u}$$

with :

- the port map defined by the vector $g = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
- input the temperature $u = T_e$ of the environment and $\tau = 1$
- function $\gamma_{\text{port}}(T_2, u) = \frac{\lambda_e}{u T_2}$ (which is well-defined for $u > 0$)

Conclusion

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- We have **discussed the Port maps** defining the pairs of conjugated port variables:
 - for reversible Port Hamiltonian Systems as a projection of a coupled system with a state space representation of the environment with linear Hamiltonian function
 - for Irreversible Port Hamiltonian Systems we have suggested an extension by introducing a second input related to the definition of an entropy function for the environment and derived the associated output port variable.
- Current and ongoing work:
 - develop time discretization schemes preserving the energy and entropy balance : with David Martin de Diego and Laurent Lefèvre
 - develop optimal control using the energy and entropy as cost functions: Timm Faulwasser, Friedrich Philipp, Manuel