

# Dissipative partial differential-algebraic equations

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MATHEMATICAL MODELLING,  
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$$\frac{d}{dt}Ex(t) = Ax(t), \quad t \geq 0, \quad Ex(0) = z_0.$$

►  $E, A \in \mathbb{C}^{n \times n}$ ,  $z_0 \in \mathbb{C}^n$ ,  $\det(\lambda E - A) \neq 0$  for some  $\lambda \in \mathbb{C}$ .

$(E, A) \sim (\tilde{E}, \tilde{A})$ , if  $T, S$  invertible exist:  $TES = \tilde{E}$ ,  $TAS = \tilde{A}$ .

Weierstraß canonical form

$(E, A) \sim \left( \begin{bmatrix} I & 0 \\ 0 & N \end{bmatrix}, \begin{bmatrix} J & 0 \\ 0 & I \end{bmatrix} \right)$ , where  $N$  is nilpotent.

Dissipativity

$$\frac{d}{dt} \|Ex(t)\|^2 \leq 0 \iff \operatorname{Re} \langle Ex(t), Ax(t) \rangle \leq 0.$$



$$\frac{d}{dt}Ex(t) = Ax(t), \quad t \geq 0, \quad Ex(0) = z_0.$$

- ▶  $\mathcal{X}$  and  $\mathcal{Z}$  are Hilbert spaces
- ▶  $E : \mathcal{X} \rightarrow \mathcal{Z}$  linear and bounded
- ▶  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{Z}$  densely defined and closed
- ▶  $z_0 \in \mathcal{Z}$
- ▶ There exists  $s \in \mathbb{C}$  such that  $sE - A$  is boundedly invertible



## Example: Dzektser equation

$$\frac{\partial}{\partial t} \left( 1 + \frac{\partial^2}{\partial \zeta^2} \right) x(\zeta, t) = \left( \frac{\partial^2}{\partial \zeta^2} + 2 \frac{\partial^4}{\partial \zeta^4} \right) x(\zeta, t),$$

$t > 0$  and  $\zeta \in (0, \pi)$ , with boundary conditions

$$x(0, t) = x(\pi, t) = 0, \quad t > 0$$

$$\frac{\partial^2 x}{\partial \zeta^2}(0, t) = \frac{\partial^2 x}{\partial \zeta^2}(\pi, t) = 0, \quad t > 0.$$

Let  $\mathcal{Z} = L^2(0, \pi)$  and  $\mathcal{X} = H^2(0, \pi) \cap H_0^1(0, \pi)$  with  $\|x\|_{\mathcal{X}}^2 = \|x''\|_{\mathcal{Z}}^2$ ,  $E \in \mathcal{L}(\mathcal{X}, \mathcal{Z})$  and  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{Z}$  given by

$$Ex = x + x'',$$

$$Ax = x'' + 2x^{(4)},$$

$$\mathcal{D}(A) = \{x \in H^4(0, \pi) \cap H_0^1(0, \pi) \mid x''(0) = x''(\pi) = 0\}.$$



# What is known?

- ▶ **Existence of solutions on a subspace:** Yagi 1991, Thaller & Thaller 1996/2001, Favini & Yagi 1999/2004, Reis & Tischendorff 2005, Reis 2008, Showalter 2010, Trostorff 2020, .....
- ▶ **"Weierstraß canonical form":**
  - **Thaller & Thaller 1996:** Investigate the splitting  $\mathcal{X} = \ker E \oplus \overline{\text{ran } E^*}$  and  $\mathcal{Z} = \ker E^* \oplus \overline{\text{ran } E}$ .
  - **Sviridyuk & Fedorov 2003:** Characterise solvability in Banach spaces and prove a canonical form.
  - **Reis 2008:** Generalization of the Weierstraß canonical form. Requires the existence of certain projections.

## Aim of this talk

Characterize DAEs  $\frac{d}{dt}Ex(t) = Ax(t)$  such that

- ▶ For  $z_0 \in \text{ran } E$ , the DAE has a solution  $x(\cdot)$ :  $\frac{d}{dt}\|Ex(t)\|^2 \leq 0$
- ▶  $(E, A) \sim \left( \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} J & 0 \\ 0 & I \end{bmatrix} \right)$



$$\dot{x}(t) = Ax(t), \quad t \geq 0, \quad x(0) = z_0.$$

- ▶  $\mathcal{X}$  is a Hilbert spaces,  $z_0 \in \mathcal{X}$
- ▶  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{X}$  densely defined and closed
- ▶ There exists  $s \in \mathbb{C}$  such that  $(sI - A)^{-1} \in \mathcal{L}(\mathcal{X})$

We call  $x : [0, \infty) \rightarrow X$  a **classical solution**, if  $x$  is continuously differentiable and  $\dot{x}(t) = Ax(t)$ ,  $t \geq 0$ , and  $x(0) = z_0$ .

We call  $x : [0, \infty) \rightarrow X$  a **mild solution**, if  $x$  is continuous and  $x(t) = z_0 + A \int_0^t x(s) ds$  for  $t \geq 0$ .

Every classical solution is a mild solution.

The following assertions are equivalent:

- ▶ for all  $z_0 \in \mathcal{X}$  there exists a unique mild solution.
- ▶ for all  $z_0 \in \mathcal{D}(A)$  there exists a unique classical solution.



$$\dot{x}(t) = Ax(t), \quad t \geq 0, \quad x(0) = z_0.$$

$\mathcal{X}$  Hilbert spaces,  $z_0 \in \mathcal{X}$ ,  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{X}$  densely defined & closed

## Hille-Yosida Theorem

The following assertions are equivalent:

- ▶ for all  $z_0 \in \mathcal{X}$  there exists a **unique bounded mild solution**.
- ▶ There is  $K \geq 1$ :  $(0, \infty) \in \rho(A)$  and  $\|(sI - A)^{-n}\|_{\mathcal{L}(\mathcal{X}, \mathcal{X})} \leq \frac{K}{s^n}$  for  $n \in \mathbb{N}$  and  $s > 0$ .

## Lumer-Phillips Theorem

The following assertions are equivalent:

- ▶ for all  $z_0 \in \mathcal{X}$  there exists a **unique mild solution with non-increasing norm**.
- ▶  $\operatorname{Re} \langle Ax, x \rangle \leq 0$  for  $x \in \mathcal{D}(A)$  and  $\operatorname{ran}(I - A) = \mathcal{X}$ .
- ▶  $\operatorname{Re} \langle Ax, x \rangle \leq 0$  for  $x \in \mathcal{D}(A)$  and  $\operatorname{Re} \langle A^*x, x \rangle \leq 0$  for  $x \in \mathcal{D}(A^*)$ .



# $E$ -radiality (Sviridyuk & Fedorov)

Resolvent set  $\varrho(E, A) := \{s \in \mathbb{C} \mid (sE - A)^{-1} \in \mathcal{L}(\mathcal{Z}, \mathcal{X})\}$

$$R^E(s, A) = (sE - A)^{-1}E, \quad L^E(s, A) = E(sE - A)^{-1},$$

The operator  $A$  is  $E$ -radial, if

- ▶  $s \in \varrho(E, A)$  for all real  $s > 0$ ,
- ▶ there exists  $K > 0$  such that for  $n \in \mathbb{N}$  and for  $s > 0$

$$\|(R^E(s, A))^n\|_{\mathcal{L}(\mathcal{X}, \mathcal{X})} \leq \frac{K}{s^n}, \quad \|(L^E(s, A))^n\|_{\mathcal{L}(\mathcal{Z}, \mathcal{Z})} \leq \frac{K}{s^n}$$

Define for some  $\alpha \in \varrho(E, A)$ ,

$$\begin{aligned} \mathcal{X}^0 &= \ker R^E(\alpha, A) = \ker E, & \mathcal{X}^1 &= \overline{\operatorname{ran} R^E(\alpha, A)}, \\ \mathcal{Z}^0 &= \ker L^E(\alpha, A), & \mathcal{Z}^1 &= \overline{\operatorname{ran} L^E(\alpha, A)}. \end{aligned}$$

These spaces are independent of the choice of  $\alpha$ .





$$\begin{aligned}\mathcal{X}^0 &= \ker R^E(\alpha, A) = \ker E, & \mathcal{X}^1 &= \overline{\operatorname{ran} R^E(\alpha, A)}, \\ \mathcal{Z}^0 &= \ker L^E(\alpha, A), & \mathcal{Z}^1 &= \overline{\operatorname{ran} L^E(\alpha, A)}.\end{aligned}$$

If,  $A$  is  $E$ -radial, then we have:

- ▶  $\mathcal{X} = \mathcal{X}^0 \oplus \mathcal{X}^1$  and  $\mathcal{Z} = \mathcal{Z}^0 \oplus \mathcal{Z}^1$ .
- ▶  $P : \mathcal{X} \rightarrow \mathcal{X}$  defined by  $Px := \lim_{s \rightarrow \infty} sR^E(s, A)x$  is a projection with
$$\ker P = \mathcal{X}^0 \text{ and } \operatorname{ran} P = \mathcal{X}^1,$$
- ▶  $Q : \mathcal{Z} \rightarrow \mathcal{Z}$  defined by  $Qz := \lim_{s \rightarrow \infty} sL^E(s, A)z$  is a projection with
$$\ker Q = \mathcal{Z}^0 \text{ and } \operatorname{ran} Q = \mathcal{Z}^1,$$
- ▶ for all  $x \in D(A)$ ,  $Px \in D(A)$  and  $APx = QAx$ ,
- ▶ for all  $x \in \mathcal{X}$ ,  $EPx = QEx$ .



Let  $A$  be  $E$ -radial. Then the operators

$$\tilde{P} = \begin{bmatrix} I - P \\ P \end{bmatrix} \in \mathcal{L}(\mathcal{X}, \mathcal{X}^0 \times \mathcal{X}^1), \quad \tilde{Q} = \begin{bmatrix} I - Q \\ Q \end{bmatrix} \in \mathcal{L}(\mathcal{Z}, \mathcal{Z}^0 \times \mathcal{Z}^1),$$

are bounded invertible.

$$\begin{aligned} \frac{d}{dt} E z = A z &\iff \frac{d}{dt} \tilde{Q} E \tilde{P}^{-1} \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} = \tilde{Q} A \tilde{P}^{-1} \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} \\ &\iff \frac{d}{dt} \begin{bmatrix} E_0 & 0 \\ 0 & E_1 \end{bmatrix} \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} = \begin{bmatrix} A_0 & 0 \\ 0 & A_1 \end{bmatrix} \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} \end{aligned}$$

If additionally  $\text{ran } E$  is closed, then we have:

- ▶  $E_0 \in \mathcal{L}(\mathcal{X}^0, \mathcal{Z}^0)$  with  $E_0 = 0$ ,
- ▶  $E_1 \in \mathcal{L}(\mathcal{X}^1, \mathcal{Z}^1)$  is boundedly invertible.
- ▶  $A_0 : D(A_0) \subset \mathcal{X}^0 \rightarrow \mathcal{Z}^0$  is densely defined, closed & boundedly invertible,
- ▶  $A_1 : D(A_1) \subset \mathcal{X}^1 \rightarrow \mathcal{Z}^1$  is densely defined and closed.



$$\frac{d}{dt}Ex(t) = Ax(t), \quad t \geq 0, \quad Ex(0) = z_0.$$

- ▶  $\mathcal{X}$  and  $\mathcal{Z}$  are Hilbert spaces,  $z_0 \in \mathcal{Z}$
- ▶  $E : \mathcal{X} \rightarrow \mathcal{Z}$  linear, bounded **with closed range**
- ▶  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{Z}$  densely defined and closed
- ▶ ( **$E$ -radial**) there exists  $K > 0$  such that for  $n \in \mathbb{N}$  and  $s > 0$   
 $\|(R^E(s, A))^n\|_{\mathcal{L}(\mathcal{X}, \mathcal{X})} \leq \frac{K}{s^n}, \quad \|(L^E(s, A))^n\|_{\mathcal{L}(\mathcal{Z}, \mathcal{Z})} \leq \frac{K}{s^n}$

## Theorem

There exists invertible operators  $T \in L(\mathcal{Z}, \mathcal{Z})$  and  $S \in L(\mathcal{X}, \mathcal{X})$ :

$$TES = \begin{bmatrix} 0 & 0 \\ 0 & I \end{bmatrix}, \quad TAS = \begin{bmatrix} I & 0 \\ 0 & A_1 E_1^{-1} \end{bmatrix}.$$

Moreover, the reduced system  $\dot{z}_1(t) = A_1 E_1^{-1} z_1(t)$ ,  $t \geq 0$ ,  $z_1(0) = z$ , has a unique mild solution for every  $z \in \mathcal{Z}_1$ .

If  $K = 1$ , then the solutions are non-increasing in norm.



$$\frac{d}{dt}Ex(t) = Ax(t), \quad t \geq 0, \quad Ex(0) = z_0.$$

We have (formally) for classical solutions

$$\frac{d}{dt}\|Ex(t)\|^2 = 2\operatorname{Re}\langle Ex(t), Ax(t)\rangle$$

and for  $s > 0$  and  $x \in \mathcal{D}(A)$

$$\begin{aligned}\|(sE - A)x\|_{\mathcal{Z}} &\geq s\|Ex\|_{\mathcal{Z}} && \iff \\ s^2\|Ex\|_{\mathcal{Z}}^2 - 2s\operatorname{Re}\langle Ex, Ax\rangle + \|Ax\|_{\mathcal{Z}}^2 &\geq s^2\|Ex\|_{\mathcal{Z}}^2 && \iff \\ \operatorname{Re}\langle Ex, Ax\rangle &\leq \frac{1}{s}\|Ax\|_{\mathcal{Z}}^2 && .\end{aligned}$$

Let  $(0, \infty) \in \rho(E, A)$ . The following are equivalent

- ▶  $\operatorname{Re}\langle Ex, Ax\rangle \leq 0$  for  $x \in \mathcal{D}(A)$ .
- ▶  $\|(sE - A)x\|_{\mathcal{Z}} \geq s\|Ex\|_{\mathcal{Z}}$  for every  $s > 0$ ,  $x \in \mathcal{D}(A)$ .
- ▶  $\|E(sE - A)^{-1}\| \leq \frac{1}{s}$  for every  $s > 0$ .



$$\frac{d}{dt}Ex(t) = Ax(t), \quad t \geq 0, \quad Ex(0) = z_0.$$

- ▶  $\mathcal{X}$  and  $\mathcal{Z}$  are Hilbert spaces,  $z_0 \in \mathcal{Z}$
- ▶  $E : \mathcal{X} \rightarrow \mathcal{Z}$  linear, bounded **with closed range**
- ▶  $A : \mathcal{D}(A) \subset \mathcal{X} \rightarrow \mathcal{Z}$  densely defined and closed
- ▶  $\lambda \in \rho(E, A)$  for some  $\lambda > 0$  and

$$\begin{aligned} \operatorname{Re} \langle Ax, Ex \rangle_{\mathcal{Z}} &\leq 0, \quad x \in \mathcal{D}(A), \\ \operatorname{Re} \langle A^*x, E^*x \rangle_{\mathcal{X}} &\leq 0, \quad x \in \mathcal{D}(A^*), \end{aligned}$$

## Theorem

There exists invertible operators  $T \in L(\mathcal{Z}, \mathcal{Z})$  and  $S \in L(\mathcal{X}, \mathcal{X})$ :

$$TES = \begin{bmatrix} 0 & 0 \\ 0 & I \end{bmatrix}, \quad TAS = \begin{bmatrix} I & 0 \\ 0 & A_1 E_1^{-1} \end{bmatrix}.$$

Moreover, the reduced system  $\dot{z}_1(t) = A_1 E_1^{-1} z_1(t)$ ,  $t \geq 0$ ,  $z_1(0) = z$ , has for every  $z \in \mathcal{Z}_1$  unique mild solution.

Further, every classical solution of the DAE satisfies  $\frac{d}{dt} \|Ex(t)\|^2 \leq 0$ .

# Can this be generalized to higher nilpotency degree?

So far:  $N = 0$ , that is, the nilpotency index is 0 or 1.

Approach can be generalized

$p$ - $E$ -radial ( $p \in \mathbb{N}$ ) instead of  $E$ -radial: There exists  $K > 0$  such that for  $n \in \mathbb{N}$  and  $s_1, \dots, s_p > 0$

$$\left\| \left( \prod_{q=0}^p R^E(s_q, A) \right)^n \right\|_{\mathcal{L}(\mathcal{X}, \mathcal{X})} \leq K \prod_{q=0}^p \frac{1}{s_q^n},$$
$$\left\| \left( \prod_{q=0}^p L^E(s_q, A) \right)^n \right\|_{\mathcal{L}(\mathcal{Z}, \mathcal{Z})} \leq K \prod_{q=0}^p \frac{1}{s_q^n}$$

Then

$$TES^{-1} = \begin{bmatrix} N & 0 \\ 0 & I \end{bmatrix},$$



## Example: Dzektser equation

$$\frac{\partial}{\partial t} \left( 1 + \frac{\partial^2}{\partial \zeta^2} \right) x(\zeta, t) = \left( \frac{\partial^2}{\partial \zeta^2} + 2 \frac{\partial^4}{\partial \zeta^4} \right) x(\zeta, t), \quad t > 0, \zeta \in (0, \pi)$$

$$x(0, t) = x(\pi, t) = 0, \quad t > 0$$

$$\frac{\partial^2 x}{\partial \zeta^2}(0, t) = \frac{\partial^2 x}{\partial \zeta^2}(\pi, t) = 0, \quad t > 0.$$

Let  $\mathcal{Z} = L^2(0, \pi)$  and  $\mathcal{X} = H^2(0, \pi) \cap H_0^1(0, \pi)$  with  $\|x\|_{\mathcal{X}}^2 = \|x''\|_{\mathcal{Z}}^2$ ,

$$Ex = x + x'',$$

$$Ax = x'' + 2x^{(4)},$$

$$\mathcal{D}(A) = \{x \in H^4(0, \pi) \cap H_0^1(0, \pi) \mid x''(0) = x''(\pi) = 0\}.$$

For  $x \in \mathcal{D}(A)$  we calculate

$$\begin{aligned} \operatorname{Re} \langle Ax, Ex \rangle_{\mathcal{Z}} &= \operatorname{Re} \int_0^\pi (x'' + 2x^{(4)})(\bar{x} + \bar{x}'') d\zeta \\ &= -\|x'\|_{L^2(0, \pi)}^2 + \|x''\|_{L^2(0, \pi)}^2 - 2\|x^{(3)}\|_{L^2(0, \pi)}^2 - 2 \operatorname{Re} \int_0^\pi x^{(3)} \bar{x}' d\zeta \\ &\leq \|x''\|_{L^2(0, \pi)}^2 - \|x^{(3)}\|_{L^2(0, \pi)}^2 \\ &\leq 0. \end{aligned}$$



# Example: Dzektser equation

It is easy to see that  $1 \in \rho(E, A)$ . Next we calculate  $A^* : \mathcal{D}(A^*) \subset \mathcal{Z} \rightarrow \mathcal{X}$ . Note that  $S : \mathcal{X} \rightarrow \mathcal{Z}$  given by  $Sf := f''$  is an isometric isomorphism with

$$(S^{-1}f)(x) = \int_0^x (x-t)f(t)dt - \frac{x}{\pi} \int_0^\pi (\pi-t)f(t)dt.$$

Then  $A^*z = S^{-1}z + 2z$  for  $z \in \mathcal{X}$ . For  $x \in \mathcal{D}(A^*) = \mathcal{X}$  and  $y = S^{-1}x$  we calculate

$$\begin{aligned} \operatorname{Re} \langle A^*x, E^*x \rangle_{\mathcal{X}} &= \operatorname{Re} \langle EA^*x, x \rangle_{\mathcal{Z}} \\ &= \operatorname{Re} \int_0^\pi (S^{-1}x + x + 2x + 2x'')\bar{x}d\zeta \\ &= \operatorname{Re} \int_0^\pi (y + y'' + 2y'' + 2y^{(4)})\bar{y}''d\zeta \\ &= -\|y'\|_{\mathcal{Z}}^2 + \|y''\|_{\mathcal{Z}}^2 \\ &\quad - 2 \operatorname{Re} \int_0^\pi y' \overline{y^{(3)}}d\zeta - 2\|y^{(3)}\|_{\mathcal{Z}}^2 \\ &= \|y''\|_{\mathcal{Z}}^2 - \|y^{(3)}\|_{\mathcal{Z}}^2 \\ &\leq 0. \end{aligned}$$





$$\frac{d}{dt} \underbrace{\begin{pmatrix} I & 0 \\ 0 & 0 \end{pmatrix}}_E x(t) = \underbrace{\begin{bmatrix} A_1 & A_2 \\ A_3 & A_4 \end{bmatrix}}_A x(t), \quad t > 0,$$

$A_i : \mathcal{D}(A_i) \subset Z \rightarrow Z$  closed & densely defined,  $\mathcal{X} = \mathcal{Z} = Z \times Z$ ,  
 $\mathcal{D}(A) = (\mathcal{D}(A_1) \cap \mathcal{D}(A_3)) \times (\mathcal{D}(A_2) \cap \mathcal{D}(A_4))$ .

- ▶ Let  $0 \in \varrho(A_4)$ ,  $\mathcal{D}(A_4) \subset \mathcal{D}(A_2)$  and  $\mathcal{D}(A_4^*) \subset \mathcal{D}(A_3^*)$  and  $A_2 A_4^{-1} A_3 \in \mathcal{L}(Z)$ .
- ▶ Let there exist  $M \geq 1$  and  $\omega \in \mathbb{R}$  such that for every  $s > \omega$ ,  $s \in \varrho(A_1)$  and  $\|(s - A_1)^{-n}\| \leq \frac{M}{(s - \omega)^n}$ ,  $s > \omega, n \in \mathbb{N}$ .

Then  $\bar{A} - \omega_0 E$  is  $E$ -radial and  $\text{ran } E$  is closed.

The projections  $P$  and  $Q$  for this class of systems are given by

$$P \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} I & 0 \\ -A_4^{-1} A_3 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

and

$$Q \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} I & -A_2 A_4^{-1} \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$



$$\begin{aligned} \frac{d}{dt}Ex(t) &= AQx(t), \quad t \geq 0, & Ex(0) &= z_0. \\ H(x) &= \langle x, E^*Qx \rangle \end{aligned}$$

- ▶  $E, Q, A \in \mathbb{C}^{n \times n}$ ,  $z_0 \in \mathbb{C}^n$ ,  $\det(\lambda E - AQ) \neq 0$  for some  $\lambda \in \mathbb{C}$ ,  $E^*Q = Q^*E \geq 0$ .

## Dissipativity

$$\frac{d}{dt}H(x) \leq 0 \iff A = J - R \text{ with } J^* = -J \text{ and } R^* = R \geq 0.$$



# Dissipative Hamiltonian DAE

$$\begin{aligned} \frac{d}{dt}Ex(t) &= AQx(t), \quad t \geq 0, & Ex(0) &= z_0. \\ H(x) &= \langle x, E^*Qx \rangle \end{aligned}$$

- ▶  $E \in L(\mathcal{X}, \mathcal{Z})$  closed range,  $Q \in L(\mathcal{X}, \mathcal{Z})$  invertible with  $E^*Q = Q^*E \geq 0$
- ▶  $A : \mathcal{D}(A) \subset \mathcal{Z} \rightarrow \mathcal{Z}$  closed &  $\operatorname{Re} \langle Ax, x \rangle \leq 0, x \in \mathcal{D}(A)$
- ▶ There exists  $s \in \mathbb{C}$  such that  $sE - AQ$  is boundedly invertible

Then there is  $X \in L(\mathcal{Z}, \mathcal{Z})$  invertible,  $X > 0$ :

$$E^*XE = E^*Q \text{ \& } H(x) = \langle Ex, XEx \rangle.$$

## Theorem

Suppose  $\operatorname{Re} \langle A^*x, x \rangle \leq 0, x \in \mathcal{D}(A^*)$ . Then there exists invertible operators  $T \in L(\mathcal{Z}, \mathcal{Z})$  and  $S \in L(\mathcal{X}, \mathcal{X})$ :

$$TES = \begin{bmatrix} 0 & 0 \\ 0 & I \end{bmatrix}, \quad TAQS = \begin{bmatrix} I & 0 \\ 0 & A_1E_1^{-1} \end{bmatrix}.$$

The reduced system  $\dot{z}_1(t) = A_1E_1^{-1}z_1(t)$ , has unique mild solutions. Further, every classical solution of the DAE satisfies  $\frac{d}{dt}H(x(t)) \leq 0$ .



# Conclusions and future work

We characterized DAEs  $\frac{d}{dt}Ex(t) = Ax(t)$  such that

- ▶ For  $x(0) \in \text{ran } E$ , the DAE has a solution  $x(\cdot)$ :  
 $\frac{d}{dt}\|Ex(t)\|^2 \leq 0$
- ▶  $(E, A) \sim \left( \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} J & 0 \\ 0 & A_1 \end{bmatrix} \right)$
- ▶ We generalized Lumer-Phillips Theorem for infinite DAEs.

Future Work:

- ▶ port-Hamiltonian DAEs in infinite-dimensional systems
- ▶ port-Hamiltonian boundary control DAEs

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B.J. and Kirsten Morris: On solvability of dissipative partial differential-algebraic equations, appears in : IEEE Control Systems Letters, 2022

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Thanks for your attention!

